

EE524 Homework 2

1. Pole-zero filter design- the goal of this problem is hand-position poles and zeros to reduce or eliminate noise in a signal. If you want to attenuate or eliminate a signal at a given frequency put a zero on the unit circle at the appropriate frequency. Putting a pole right inside this zero gives a nice sharp notch filter.

a. Download the signal `whale82000.wav`. This is a signal of killer whale calls with some sinusoidal interference at two unknown frequencies. The sampling frequency is 8 kHz.

First you need to do a spectral analysis to find the location of the interfering signals.

Design a filter with 2 zeros and 2 poles(in conjugate pairs) that eliminates the sinusoidal interference. Turn in the spectral plot of the signal, a pole-zero diagram, and the magnitude response for the filter. Comment on what you hear when you play the signal.

b. Using the signal `whale82000chirp.wav`. This time the interference is an FM signal that changes frequency in time. Use the spectrum or a spectrogram to see the frequency of this signal. Design a filter using pole-zero placement that has real coefficients which eliminate the interference. Turn in a pole-zero diagram and the magnitude response for the filter. Comment on what you hear when you play the signal.

Matlab Notes:

i. Use `wavread` to read in signals. (`wavwrite` will write a .wav file)

```
>[x,fs]=wavread('whale82.wav');
```

ii. Design the filter in pole-zero form with a vector of poles and a vector of zeros, use `zp2tf` function to convert to a transfer function and `filter` to filter the signal.

iii. Your code should have this form:

```
% read in file
[x,fs]= wavread('whale82.wav');
% define column vectors with poles and zeros, plot results in the complex z-plane
z=[ . . .]; p=[ . . .]; zplane(z,p);
% put into transfer function form
[num,den]=zp2tf(z,p,1);
% filter the signal
xf=filter(x,num,den);
```

2. Find and explain the DFT of the following sequences. Comment on the physical and computational resolution and sketch the magnitude response of the DFT (remember: it is

a discrete signal). In this case please work out the derivation in detail for part a (just for practice).

$$\text{a. } x_a[l] = \cos\left(\frac{3.5 \pi l}{8}\right), \quad l=0,1,\dots,15 \quad N=32.$$

$$\text{b. } x_b[l] = \cos\left(\frac{3.5 \pi l}{8}\right) \quad l=0,1,\dots,15 \quad N=16$$

$$\text{c. } x_c[l] = \cos\left(\frac{3.5 \pi l}{8}\right) \quad l=0,1,\dots,15 \quad N=64$$

3. Problem 4.18 from the textbook

4. Problem 4.34 from the textbook

5. Problem 4.17

6. Problem 4.65